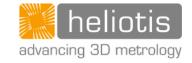
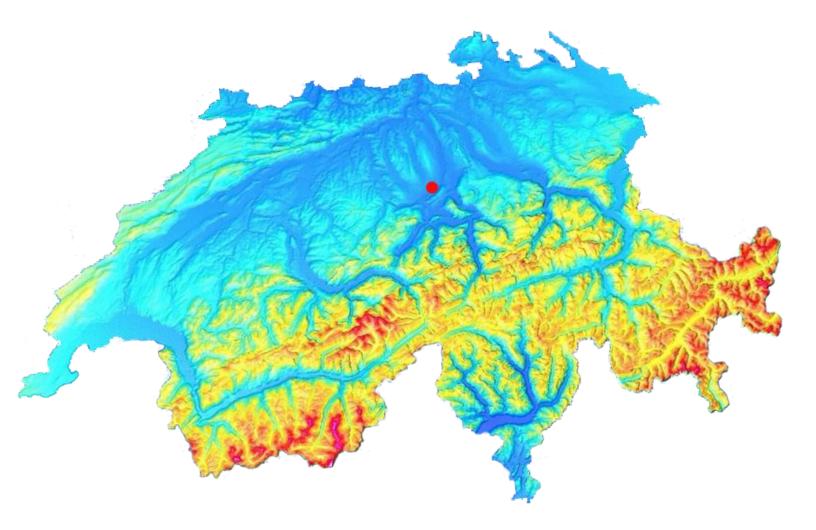


# High-Resolution 3D Sensors for Automated Inspection of Microstructures and Surfaces

"Measure what is measurable and make measurable what is not so."

# 3D Topologies hold a lot of details





# Switzerland

- North/South: 220 km
- West/East: 348 km
- Area: 41'285 km<sup>2</sup>
- Lowest point : 193m asl.
- Highest point: 4636 m
- Area above 2000m : 23%
- Mountains > 4000m : 48

Source: swisstopo

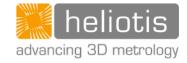
Now, scale the model down by 1 : 100 000 000 => 1km becomes 10um

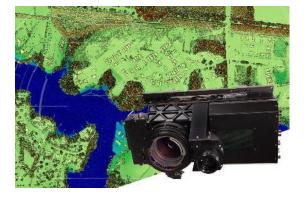
dvancing 3D metrology

Then, the heliInspect H8/H9 can measure in one FOV the entire 3D topology

- in less than 100 ms
- with a real-world resolution of 350 m x 350 m
- with a real-world height uncertainty of 0.4 m

## Actually, this has been done ...

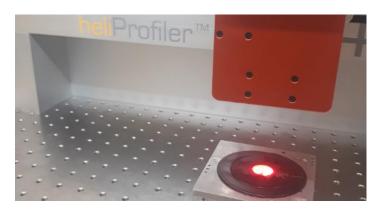




1. The terrain of Switzerland was measured optically with a Leica Topographic LIDAR Sensor



2. The topology was machined optically into metal via fs-Laser and molded into black plastic



3. The miniature topology was measured optically with the industrial White Light Interferometer heliInspect H6

# Heliotis – Advancing 3D Metrology

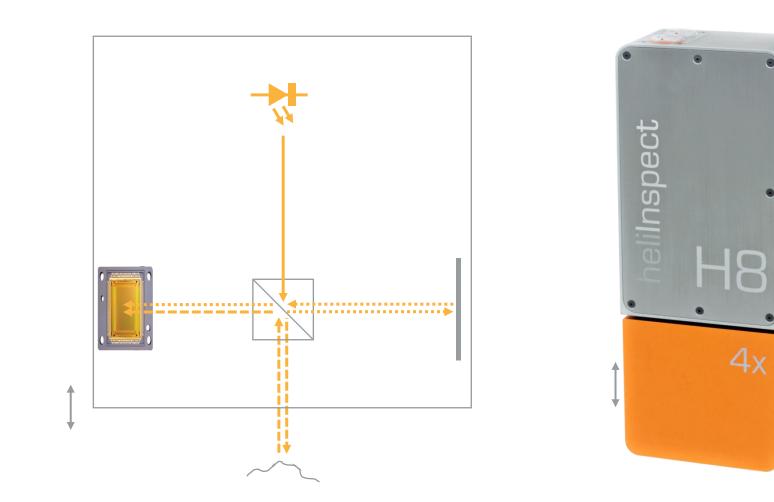
# Specialized in 3D metrology for precision applications

- in-house R&D
- in-house assembly and quality assurance
- application-specific designs



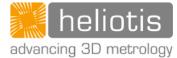
### White Light Interferometry





# Characteristics of White Light Interferometry

WWW



### Advantages

- nanometer resolution (interferometric)
- applicable to all surfaces (specular, matt, transparent)
- can do tomography
- can measure deep boreholes (no shadowing effect)

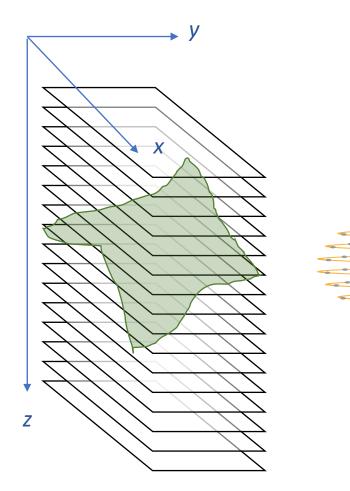
### Challenges

- very data intensive / slow
- signal dynamic high

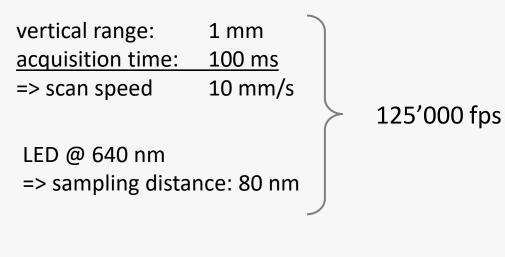
one full image every  $\lambda/8$  dz ~ 80 nm

### Speed Requirements for the Camera





#### Example:

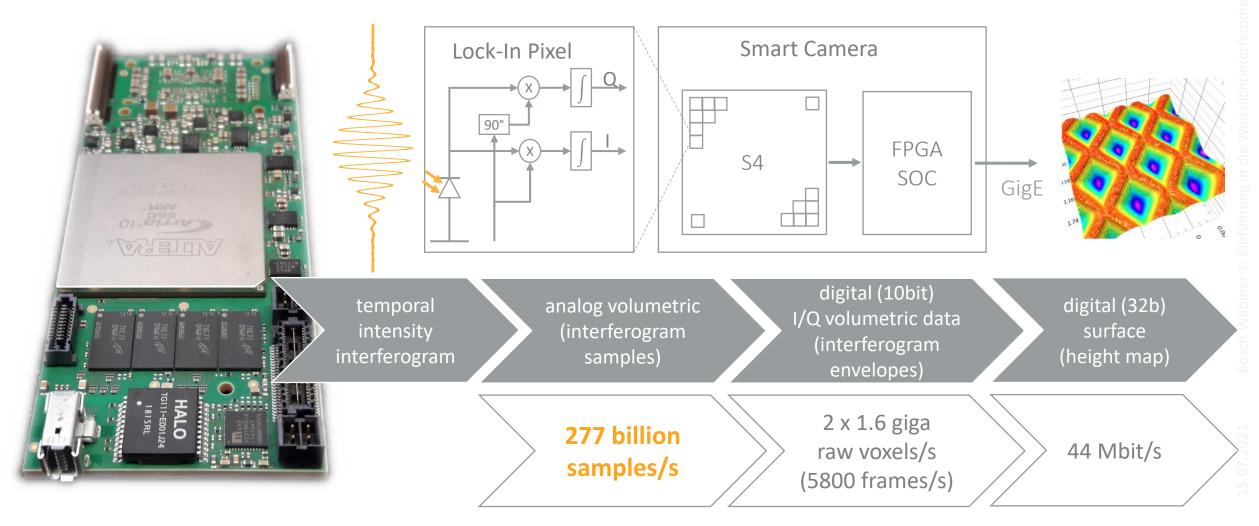


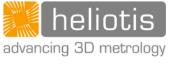
Data rate

1Mpix, 16bit  $\implies$  **2 Tbit/s** 

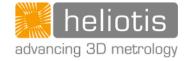
**→** Limitation: acquistion & data transfer

### In-Pixel Signal Processing Plus, FPGA-Based Post Processing

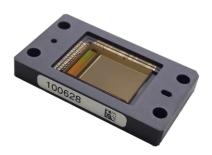




## Core Competencies in Deep Tech







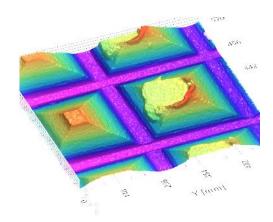
CMOS Image Sensors

- ASIC development
- pixel-IP
- high-speed interfaces
- fabless
- testing inhouse

Embedded High-Speed Cameras

- high-density PCBs
- FPGA algorithms
- embedded Linux apps
- standard based interfaces



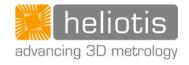


#### **Opto-Mechanics**

- optics simulations
- CAD engineering
- sourcing
- assembly (ISO 5)
- testing

#### **3D Image Processing**

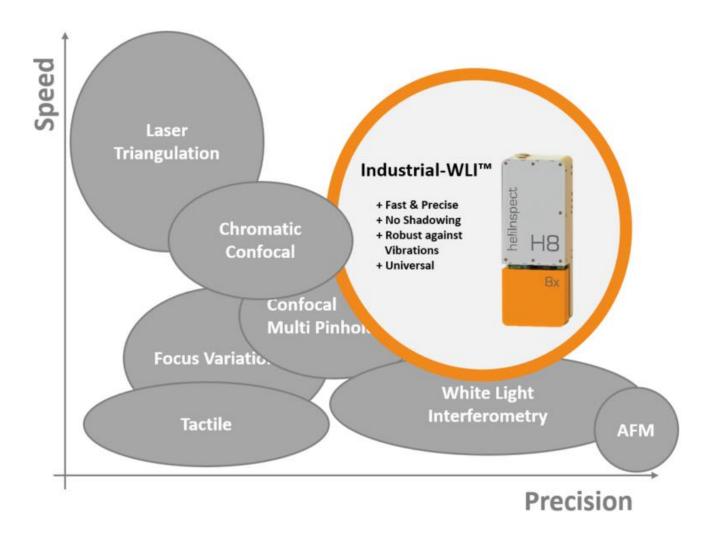
Halcon, Matrox, Aurora
Vision, Neurocheck,
C++, C#, LabView, Python



# High Precision Industrial 3D Inspection = Precision x Speed

#### Industrial WLI<sup>™</sup> H8 / H9

- geometry
- defects
- planarity
- layer thickness
- surface quality
- transparent materials
- mirroring surfaces



# Interferometric Repeatability No vibration cancelation required





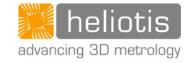




Standard	Step height	Measured Repeatability	Mode
VLSI /NIST	9.9 nm	0.3 nm	Phase
VLSI /NIST	99.6 nm	0.4 nm	Phase
VLSI / NIST	4.5 um	0.004 um	Envelope
VLSI / PTB	201.603 um	0.044 um	Envelop
РТВ	899.941 um	0.063 um	Envelope



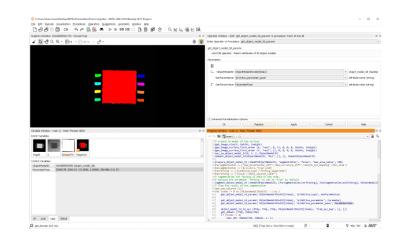
### Where are these sensors used?





#### **OEM** Partners

- inspection machines
- 3D-metrology vendors
- medical diagnostics
- forensic equipment





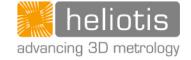
#### **Vision Integrators**

- defect detection
- process control
- geometry
- layer thickness
- surface quality

#### Machine Builder & Producers

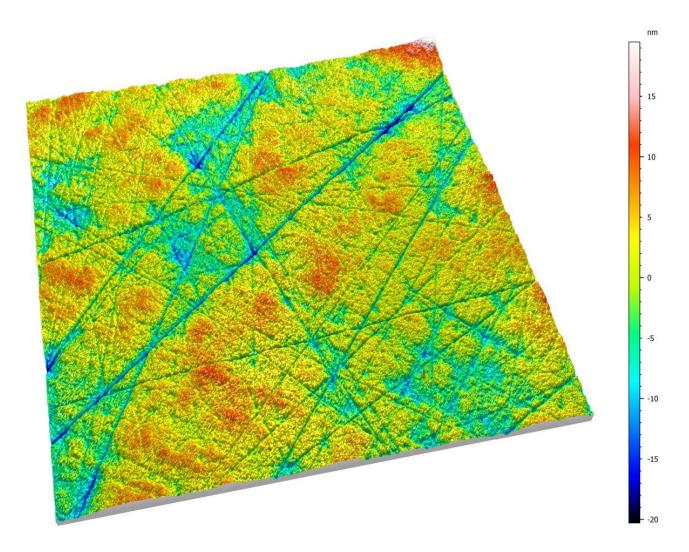
- automotive
- electronics
- medical technologies
- watch industry

# Measurements on glass with nanometer accuracy

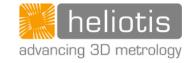


Proprietary phase algorithms for exceptional height resolution

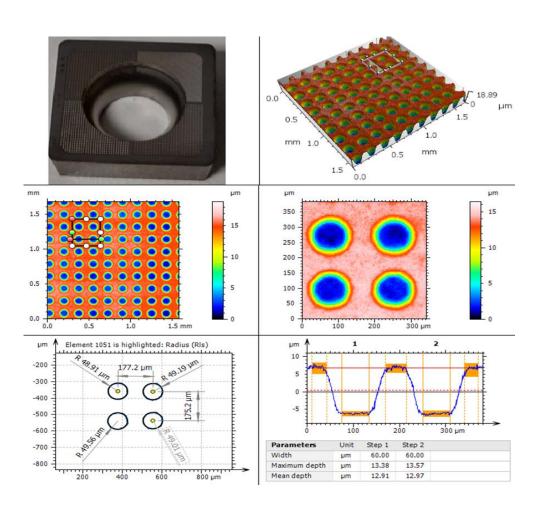
Roughness measurement < 0.2 nm

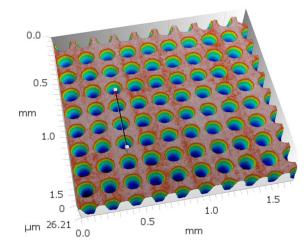


#### Micro-Patterning with 3 kW femtosecond laser



#### ---FEMTO SURF



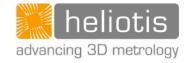


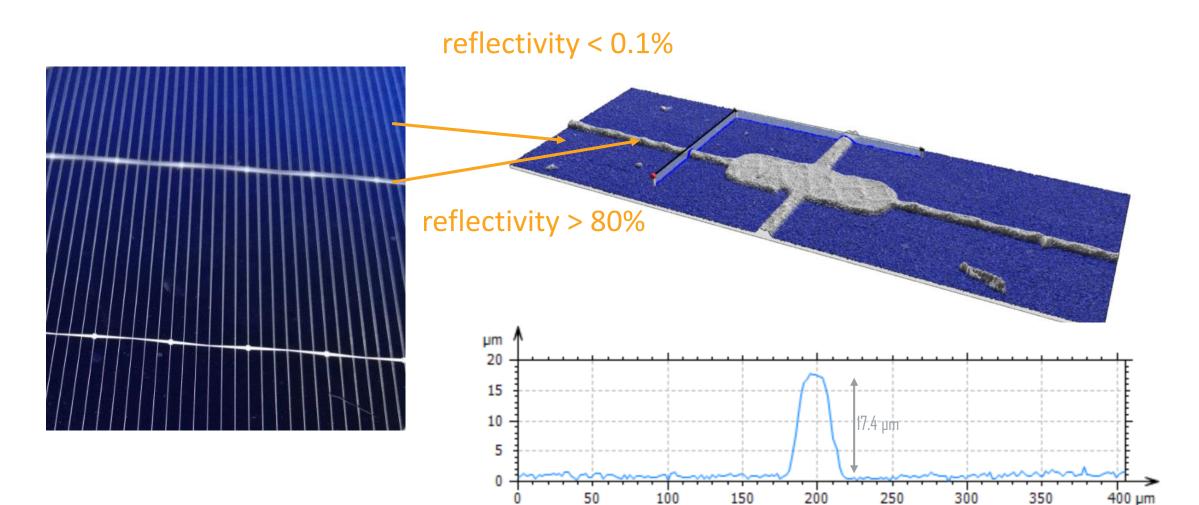


These micro-features are laser textured on the surface of the cemented carbide lathing insert to reduce the cutting forces, and friction between tool rake face and chip during the machining process. It also has shown that it the dimples and grooves can promote hydrodynamic regime transition on the tool's cutting face and hence improving tool life/service performance.

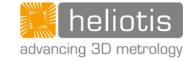
ISO 25178 - Roughness (S-L) S-filter (As): Robust Gaussian (order 0), 0.8 µm F-operation: Leveled (TLS), Angle 0.03278°, -0.002131° L-filter (Ac): Robust Gaussian (order 0), 0.1 mm Height parameters	Roughness measurement of laser pr	ocessed surfaces	heliotis advancing 3D metrology
Sq 4.029 µm Root-mean-square height   Sa 3.207 µm Arithmetic mean height   Spatial parameters   Sal 5.157 µm Autocorrelation length   Functional parameters (volume)	FEMTO SURF	:	
Vv   5.975   µm³/µm²   Void Volume     Functional parameters (stratified surfaces)     Sk   9.009   µm   Care height     ISO 4287 - Roughness (S-L)     F-operation: Leveled (TLS), Angle 0.0008209°     S-filter (As): Robust Gaussian (order 0), 0.8 µm     L-filter (Ac): Robust Gaussian (order 0), 0.1 mm     Evaluation length: All Ac (18)     Amplitude parameters     Rv   7.311   µm   Maximum valley depth of the roughn     Ra   2.960   µm   Arithmetic mean deviation of the rou     Rq   3.677   µm   Root-mean-square (RMS) deviation o	47 $\mu$ m $6^{-1}$ 8P 5 $100100 \mum 150100 \mum 150 100 \mum 100$	86.56 40 100 100 100 100 100 100 100	
42.84 μm ,	<sup>20</sup> <sup>8</sup> P 10 <sup>20</sup> <sup>8</sup> P 10 <sup>20</sup> <sup>10</sup> <sup>10</sup> <sup>10</sup> <sup>10</sup> <sup>10</sup> <sup>10</sup> <sup>10</sup> <sup>1</sup>	8P 20 6 5 100 µm 150 200 0	<sup>200</sup> <sup>6</sup> 8P 30 <sup>9</sup> 8P 30 <sup>9</sup> <sup>100</sup> <sup>100</sup> <sup>100</sup> <sup>100</sup> <sup>100</sup> <sup>100</sup> <sup>200</sup>

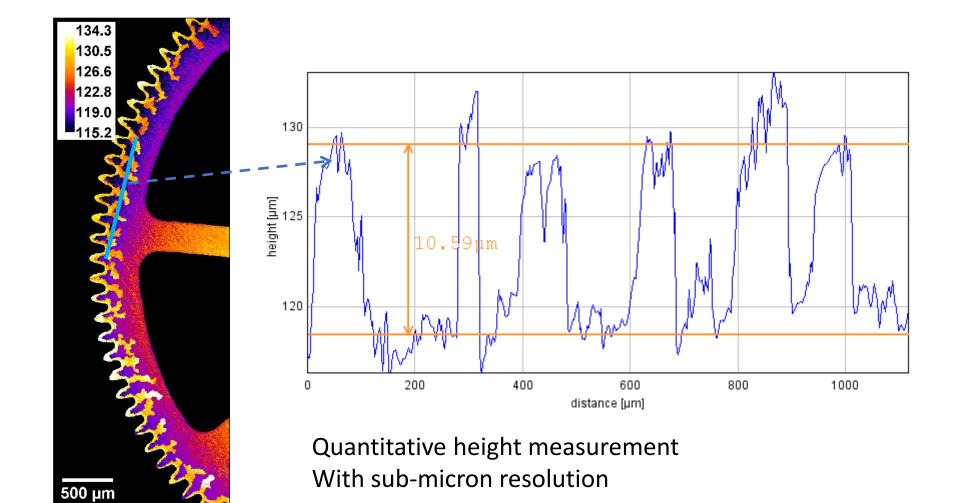
### Silver paste inspection on solar cells





### Edge defects on a gear





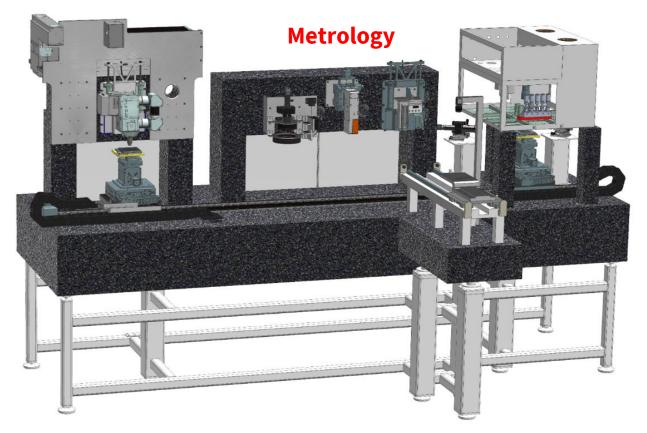
**Combination of Laser & Metrology** 



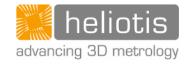
### MESIMISPH

Laser cutting/welding2 Photon Polymerisation (2PP)

Selective Area Direct Atomic Layer Processing (SADALP)



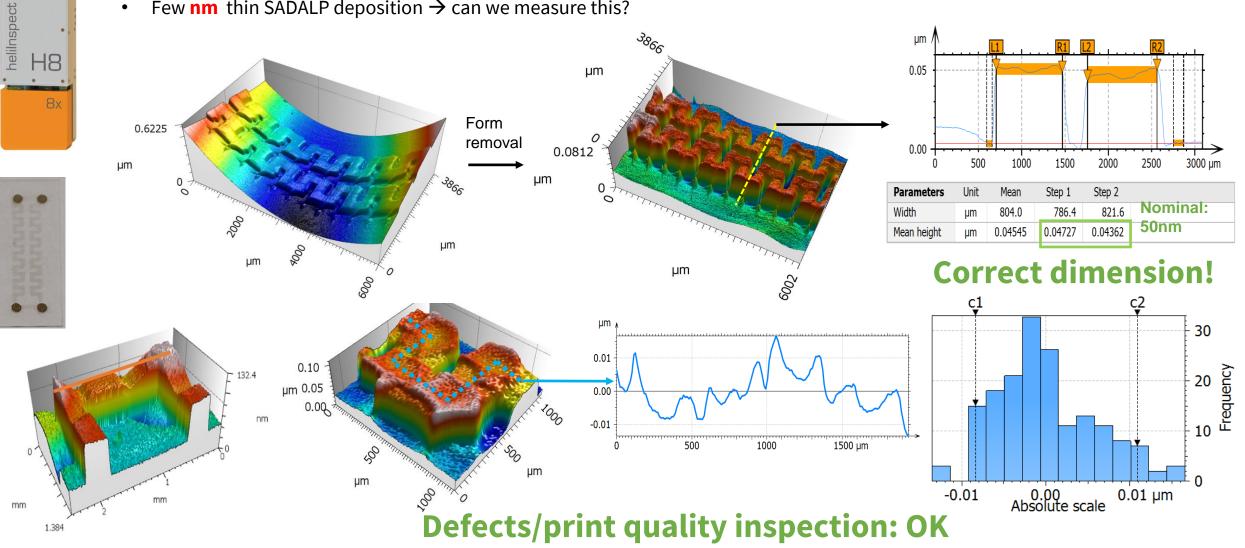
### Measurement of Atomic deposition



### ヨリリコヨリン

#### Aspects:

Few **nm** thin SADALP deposition  $\rightarrow$  can we measure this?



### Inspection of glass laser welding





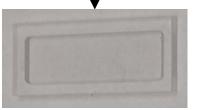
#### Aspects:

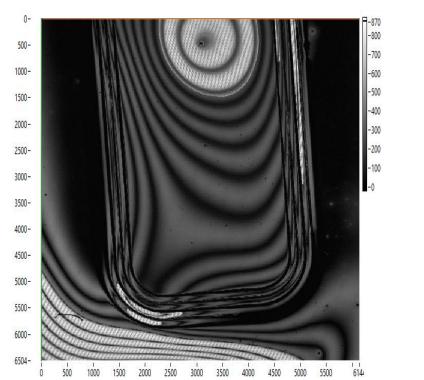
- Glass welding and imperfections → can we measure this?
- WLI is tomographic and detects interfaces where optical index changes

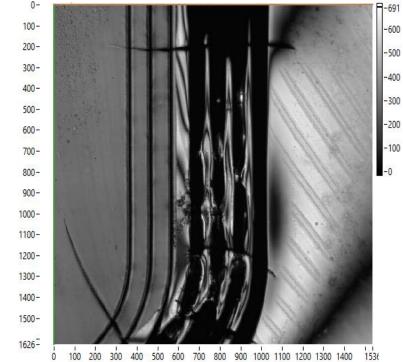


helilnspect

H8







#### Laser glass welding cracks : OK

### Measurement of 2PP printed structure





#### Aspects:

A COLORED

helilnspect

2PP

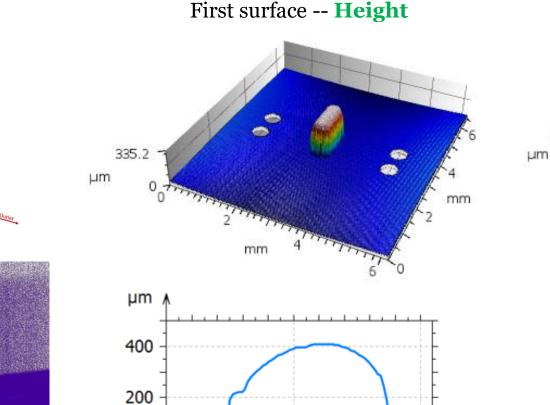
H8

SLE: hole

- 2 Photon polymerization cavity  $\rightarrow$  can we measure this?
- WLI  $\rightarrow$  tomographic ٠

0

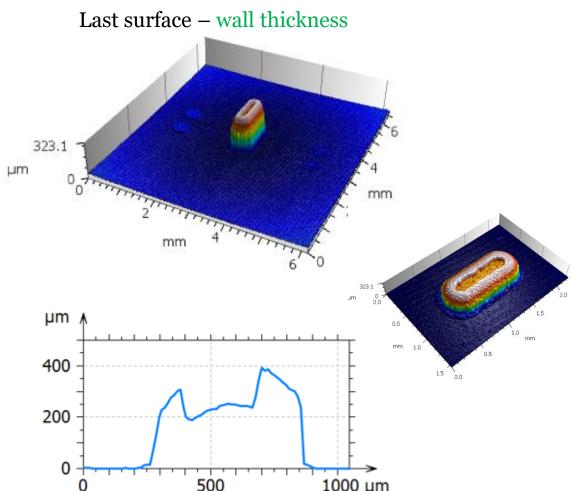
0



500

1000 µm

0



1000 µm

# If you want to learn more

Visit www.heliotis.com

Arrange a web meeting web@heliotis.com

Contact me <u>Patrick.Lambelet@heliotis.com</u>

